REFERENCES:
1. Yi-Ping Phoebe Chen (Ed), “Bio Informatics Technologies”, First Indian Reprint, Springer Verlag, 2007.
2. N.J. Chikhale and Virendra Gomase, "Bioinformatics- Theory and Practice", Himalaya Publication House, India, 2007
3. Zoe lacroix and Terence Critchlow, “Bio Informatics – Managing Scientific data”, First Indian Reprint, Elsevier, 2004
4. Bryan Bergeron, “Bio Informatics Computing”, Second Edition, Pearson Education, 2003.
5. Arthur M Lesk, “Introduction to Bioinformatics”, Second Edition, Oxford University Press, 2005
6. Burton. E. Tropp, “Molecular Biology: Genes to Proteins “, 4th edition, Jones and Bartlett Publishers, 2011
7. Dan Gusfield, “Algorithms on Strings Trees and Sequences”, Cambridge University Press, 1997.
8. P. Baldi, S Brunak , Bioinformatics, “A Machine Learning Approach “, MIT Press, 1998.

CP7026 SOFTWARE QUALITY ASSURANCE L T P C
3 0 0 3

OBJECTIVES:
- Describe approaches to quality assurance
- Understand quality models
- Evaluate the system based on the chosen quality model

UNIT I INTRODUCTION 9
Introduction – Views on quality – Cost of quality - Quality models – Quality frameworks – Verification and Validation – Defect taxonomy – Defect management – Statistics and measurements – IEEE standards – Quality assurance and control processes

UNIT II VERIFICATION 6
Introduction – Verification techniques – Inspections, reviews, walk-throughs – Case studies

UNIT III TEST GENERATION 12
Software testing- Validation – Test plan – Test cases - Test Generation – Equivalence partitioning – Boundary value analysis – Category partition method – Combinatorial generation - Decision tables – Examples and Case studies

UNIT IV STRUCTURAL TESTING 12
Introduction – Test adequacy criteria – Control flow graph – Coverages: block, conditions, multiple conditions, MC/DC, path – Data flow graph – Definition and use coverages – C-use, P-use, Def-clear, Def-use – Finite state machines – Transition coverage – Fault based testing – Mutation analysis – Case studies

UNIT V FUNCTIONAL TESTING 6
Introduction – Test adequacy criteria - Test cases from use cases – Exploratory testing - Integration, system, acceptance, regression testing – Testing for specific attributes: Performance, load and stress testing – Usability testing – Security testing - Test automation – Test oracles

TOTAL : 45 PERIODS

OUTCOMES:
Upon Completion of the course, the students will be able to
- Describe different approaches to testing software applications
- Analyze specifications and identify appropriate test generation strategies
- Develop an appropriate test design for a given test object
- Identify applicatble measurements for the verification and validation effort
- Execute the test design
- Evaluate the testing effort based on adequate measures

REFERENCES:

1. Boriz Beizer, "Software Testing Techniques", 2nd Edition, DreamTech, 2009.
2. Aditya P. Mathur, "Foundations of Software Testing", Pearson, 2008
3. Mauro Pezze and Michal Young, "Software Testing and Analysis. Process, Principles, and Techniques", John Wiley 2008
4. Stephen H. Kan, "Metrics and Models in Software Quality Engineering", 2nd Edition, Pearson, 2003
5. Kshirasagar Naik and Priyadarshi Tripathy (Eds), "Software Testing and Quality Assurance: Theory and Practice", John Wiley, 2008
6. "Combinatorial Methods in Software Testing", ttp://csrc.nist.gov/groups/SNS/acts/index.html

CP7027 MULTI OBJECTIVE OPTIMIZATION TECHNIQUES L T P C
3 0 0 3

OBJECTIVES:

- Learn fundamental principles of Multiobjective Optimization (MOP)
- Survey different Multiobjective Optimization algorithms
- Introduce various design issues of MOP
- Develop and Evaluate MOP Algorithms
- Learn Parallel and hybrid MOP Algorithms
- Learn other Metaheuristics

UNIT I INTRODUCTION AND CLASSICAL APPROACHES 9

Multiobjective optimization: Introduction - Multiobjective optimization problem-principles – Difference between single and multiobjective optimization – Dominance and Pareto Optimality , Classical Methods – Weighted Sum - □ Constraint method – Weighted Metric methods – Benson's method - Value Function - Goal Programming methods – Interactive Methods

UNIT II MOP EVOLUTIONARY ALGORITHMS 9

Generic MOEA - Various MOEAs: MOGA, NSGA-II, NPGA, PAES, SPEA2, MOMGA, micro GA - Constrained MOEAs: Penalty Function approach - Constrained Tournament – Ray – Tai –Seow's Method.

UNIT III THEORETICAL ISSUES 9

Fitness Landscapes - Fitness Functions - Pareto Ranking - Pareto Niching and Fitness Sharing - Recombination Operators - Mating Restriction - Solution Stability and Robustness - MOEA Complexity - MOEA Scalability - Running Time Analysis - MOEA Computational Cost - No Free Lunch Theorem.

UNIT IV MOEA TESTING, ANALYSIS, AND PARALLELIZATION 9

MOEA Experimental Measurements – MOEA Statistical Testing Approaches – MOEA Test Suites - MOEA Parallelization: Background – Paradigms – Issues - MOEA Local Search Techniques.

UNIT V APPLICATIONS AND ALTERNATIVE METAHEURISTICS 9

Scientific Applications: Computer Science and Computer Engineering - Alternative Metaheuristics: Simulated Annealing – Tabu Search and Scatter Search – Ant System – Distributed Reinforcement Learning – Particle Swarm Optimization – Differential Evolution – Artificial Immune Systems - Other Heuristics.

TOTAL:45 PERIODS

OUTCOMES:

Upon Completion of the course,students will be able to

- Explain MOP principles
- Explain classical methods to solve MOP problems
- Be familiar with and explain structures of different MOP algorithms
- Solve constrained MOP problems
- Explain various design issues of MOP algorithms
- Perform a evaluation and analysis of MOP algorithm results
- Explain parallelization of MOP algorithms
- Develop parallel and hybrid MOP algorithms
- Identify various real time MOP applications
- Explain other search algorithms

REFERENCES:

1. Carlos A. Coello Coello, Gary B. Lamont, David A. Van Veldhuizen, "Evolutionary Algorithms for Solving Multi-objective Problems", Second Edition, Springer, 2007.
2. Kalyanmoy Deb, " Multi-Objective Optimization Using Evolutionary Algorithms", John Wiley, 2002.
3. Aimin Zhoua, Bo-Yang Qub, Hui Li c, Shi-Zheng Zhaob, Ponnuthurai Nagaratnam Suganthan b, Qingfu Zhangd, "Multiobjective evolutionary algorithms: A survey of the state of the art", Swarm and Evolutionary Computation (2011) 32–49.
4. E Alba, M Tomassini, "Parallel and evolutionary algorithms", Evolutionary Computation, IEEE Transactions on 6 (5), 443-462.
5. Crina Grosan, Ajith Abraham, "Hybrid Evolutionary Algorithms: Methodologies, Architectures, and Reviews", Studies in Computational Intelligence, Vol. 75, Springer, 2007.
6. Christian Blum and Andrea Roli. 2003. Metaheuristics in combinatorial optimization: Overview and conceptual comparison. *ACM Comput. Surv.* 35, 3 (September 2003), 268-308.

CP7028 ENTERPRISE APPLICATION INTEGRATION L T P C
3 0 0 3

OBJECTIVES:

- Describe approaches to enterprise application integration
- Understand the integration middleware
- Evaluate the integration approaches suitable for a given problem

UNIT I INTRODUCTION 6

Requirements for EAI - Challenges in EAI – Integration with legacy systems – Integration with partners - Heterogeneous environment – Implementation approaches – Web services, messaging, ETL, direct data integration – Middleware requirements – Approaches to integration – services oriented and messaging.

UNIT II INTEGRATION PATTERNS 6

Introduction to integration patterns – Architecture for application integration – Integration patterns – Point to point, broker, message bus, publish/subscribe, Challenges in performance, security, reliability - Case studies

UNIT III SERVICE ORIENTED INTEGRATION 12

Business process integration - Composite applications-services – Web services – Service choreography and orchestration - Business process modeling - BPMN, Business process execution - BPEL – Middleware infrastructure - Case studies

UNIT IV MESSAGING BASED INTEGRATION 9

Messaging – Synchronous and asynchronous – Message structure – Message oriented middleware – Reliability mechanisms – Challenges – Messaging infrastructure – Java Messaging Services – Case studies

UNIT V ENTERPRISE SERVICE BUS 12

Enterprise Service Bus – routing, scalable connectivity, protocol and message transformations, data enrichment, distribution, correlation, monitoring – Deployment configurations – Global ESB, Directly connected, Federated, brokered ESBs – Application server based – Messaging system based – Hardware based ESBs – Support to SOA, message based and event based integrations - Case studies.

TOTAL: 45 PERIODS

OUTCOMES:

Upon Completion of the course,the students will be able to

- Describe different approaches to integration enterprise applications
- Analyze specifications and identify appropriate integration approaches
- Develop a suitable integration design for a given problem
- Identify appropriate integration middleware for a given problem
- Evaluate the integration approaches against specified requirements

REFERENCES:

1. George Mentzas and Andreas Frezen (Eds), "Semantic Enterprise Application Integration for Business Processes: Service-oriented Frameworks", Business Science Reference, 2009
2. Waseem Roshen, "SOA Based Enterprise Integration", Tata McGrawHill, 2009.
3. G □Hohpe□ and □B □Woolf,□ "Enterprise □Integration Patterns:□Designing,□ Building, □and□ Deploying□ Messaging□ Solutions",□Addison□Wesley□ Professional, 2003□
4. D □Linthicum, "Next □Generation □Application □Integration: □From□ Simple Information □to□ Web□Services",□Addison□Wesley, □2003□
5. Martin Fowler, "Patterns of Enterprise Application Architecture", Addison- Wesley, 2003
6. Kapil Pant and Matiaz Juric, "Business Process Driven SOA using BPMN and BPEL: From Business Process Modeling to Orchestration and Service Oriented Architecture", Packt Publishing, 2008

CP7029 INFORMATION STORAGE MANAGEMENT L T P C
3 0 0 3

UNIT I INTRODUCTION TO STORAGE TECHNOLOGY 9

Review data creation and the amount of data being created and understand the value of data to a business, challenges in data storage and data management, Solutions available for data storage, Core elements of a data center infrastructure, role of each element in supporting business activities

UNIT II STORAGE SYSTEMS ARCHITECTURE 9

Hardware and software components of the host environment, Key protocols and concepts used by each component ,Physical and logical components of a connectivity environment ,Major physical components of a disk drive and their function, logical constructs of a physical disk, access characteristics, and performance Implications, Concept of RAID and its components, Different RAID levels and their suitability for different application environments: RAID 0, RAID 1, RAID 3, RAID 4, RAID 5, RAID 0+1, RAID 1+0, RAID 6, Compare and contrast integrated and modular storage systems ,Iligh-level architecture and working of an intelligent storage system

UNIT III INTRODUCTION TO NETWORKED STORAGE 9

Evolution of networked storage, Architecture, components, and topologies of FC-SAN, NAS, and IP-SAN, Benefits of the different networked storage options, understand the need for long-term archiving solutions and describe how CAS full fill the need, understand the appropriateness of the different networked storage options for different application environments

UNIT IV INFORMATION AVAILABILITY, MONITORING & MANAGING DATACENTER 9

List reasons for planned/unplanned outages and the impact of downtime, Impact of downtime - Differentiate between business continuity (BC) and disaster recovery (DR) ,RTO and RPO, Identify single points of failure in a storage infrastructure and list solutions to mitigate these failures, Architecture of backup/recovery and the different backup/ recovery topologies, replication technologies and their role in ensuring information availability and business continuity, Remote replication technologies and their role in providing disaster recovery and business continuity capabilities. Identify key areas to monitor in a data center, Industry standards for data center monitoring and management, Key metrics to monitor for different components in a storage infrastructure, Key management tasks in a data center

UNIT V SECURING STORAGE AND STORAGE VIRTUALIZATION 9

Information security, Critical security attributes for information systems, Storage security domains, List and analyzes the common threats in each domain, Virtualization technologies, block-level and file-level virtualization technologies and processes

TOTAL: 45 PERIODS

REFERENCE BOOKS:

1. EMC Corporation, Information Storage and Management, Wiley, India.
2. Robert Spalding, “Storage Networks: The Complete Reference“, Tata McGraw Hill , Osborne, 2003.
3. Marc Farley, “Building Storage Networks”, Tata McGraw Hill ,Osborne, 2001.
4. Additional resource material on www.emc.com/resource-library/resource-library.esp

CP7030 ROBOTICS L T P C
3 0 0 3

OBJECTIVES:

- To understand robot locomotion and mobile robot kinematics
- To understand perception in robotics
- To understand mobile robot localization
- To understand mobile robot mapping
- To understand simultaneous localization and mapping (SLAM)
- To understand robot planning and navigation

UNIT I LOCOMOTION AND KINEMATICS 9

Introduction to Robotics – key issues in robot locomotion – legged robots – wheeled mobile robots – aerial mobile robots – introduction to kinematics – kinematics models and constraints – robot maneuverability

UNIT II ROBOT PERCEPTION 9

Sensors for mobile robots – vision for robotics – cameras – image formation – structure from stereo – structure from motion – optical flow – color tracking – place recognition – range data

UNIT III MOBILE ROBOT LOCALIZATION 9

Introduction to localization – challenges in localization – localization and navigation – belief representation – map representation – probabilistic map-based localization – Markov localization – EKF localization – UKF localization – Grid localization – Monte Carlo localization – localization in dynamic environments

UNIT IV MOBILE ROBOT MAPPING 9

Autonomous map building – occupancy grip mapping – MAP occupancy mapping – SLAM – extended Kalman Filter SLAM – graph-based SLAM – particle filter SLAM – sparse extended information filter – fastSLAM algorithm

UNIT V PLANNING AND NAVIGATION 9

Introduction to planning and navigation – planning and reacting – path planning – obstacle avoidance techniques – navigation architectures – basic exploration algorithms

TOTAL: 45 PERIODS

OUTCOMES:

Upon Completion of the course,the students will be able to

- Explain robot locomotion
- Apply kinematics models and constraints
- Implement vision algorithms for robotics
- Implement robot localization techniques
- Implement robot mapping techniques
- Implement SLAM algorithms
- Explain planning and navigation in robotics

REFERENCES:

1. Roland Seigwart, Illah Reza Nourbakhsh, and Davide Scaramuzza, “Introduction to autonomous mobile robots”, Second Edition, MIT Press, 2011.
2. Sebastian Thrun, Wolfram Burgard, and Dieter Fox, “Probabilistic Robotics”, MIT Press, 2005.
3. Howie Choset et al., “Principles of Robot Motion: Theory, Algorithms, and Implementations”, A Bradford Book, 2005.
4. Gregory Dudek and Michael Jenkin, “Computational Principles of Mobile Robotics”, Second Edition, Cambridge University Press, 2010.
5. Maja J. Mataric, “The Robotics Primer”, MIT Press, 2007.

CP7031 COMPILER OPTIMIZATION TECHNIQUES L T P C
3 0 0 3

OBJECTIVES:

- To understand the optimization techniques used in compiler design.
- To be aware of the various computer architectures that support parallelism.
- To become familiar with the theoretical background needed for code optimization.
- To understand the techniques used for identifying parallelism in a sequential program.
- To learn the various optimization algorithms.

UNIT I INTRODUCTION 9

Language Processors - The Structure of a Compiler – The Evolution of Programming Languages- The Science of Building a Compiler – Applications of Compiler Technology Programming Language Basics - The Lexical Analyzer Generator -Parser Generator - Overview of Basic Blocks and Flow Graphs - Optimization of Basic Blocks - Principle Sources of Optimization.

UNIT II INSTRUCTION-LEVEL PARALLELISM 9

Processor Architectures – Code-Scheduling Constraints – Basic-Block Scheduling –Global Code Scheduling – Software Pipelining.

UNIT III OPTIMIZING FOR PARALLELISM AND LOCALITY-THEORY 9

Basic Concepts – Matrix-Multiply: An Example - Iteration Spaces - Affine Array Indexes – Data Reuse Array data dependence Analysis.

UNITIV OPTIMIZING FOR PARALLELISM AND LOCALITY – APPLICATION 9

Finding Synchronization - Free Parallelism – Synchronization Between Parallel Loops – Pipelining – Locality Optimizations – Other Uses of Affine Transforms.

UNIT V INTERPROCEDURAL ANALYSIS 9

Basic Concepts – Need for Interprocedural Analysis – A Logical Representation of Data Flow – A Simple Pointer-Analysis Algorithm – Context Insensitive Interprocedural Analysis - Context-Sensitive Pointer-Analysis - Datalog Implementation by Binary Decision Diagrams.

TOTAL: 45 PERIODS

REFERENCES:

1. Alfred V. Aho, Monica S.Lam, Ravi Sethi, Jeffrey D.Ullman, “Compilers:Principles, Techniques and Tools”, Second Edition, Pearson Education,2008.
2. Randy Allen, Ken Kennedy, “Optimizing Compilers for Modern Architectures: A Dependence-based Approach”, Morgan Kaufmann Publishers, 2002.
3. Steven S. Muchnick, “Advanced Compiler Design and Implementation”,Morgan Kaufmann Publishers - Elsevier Science, India, Indian Reprint 2003.